JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY: KAKINADA
KAKINADA – 533 003, Andhra Pradesh, India
DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING

COURSE STRUCTURE-R19

III Year – I SEMESTER

S. No	Course Code	Subjects	Category	L	T	P	Credits
1		Power Systems-II	EE	3	--	--	3
2		Power Electronics	EE	3	--	--	3
3		Linear IC Applications	ES	3	--	--	3
4		Digital Signal Processing	EE	3	--	--	3
5		Microprocessors and Microcontrollers	EE	3	--	--	3
6		Electrical Machines-II Laboratory	EE	--	--	3	1.5
7		Control Systems Laboratory	EE	--	--	2	1
8		Electrical Measurements & Instrumentation Laboratory	EE	--	--	3	1.5
9		Socially Relevant Projects	MC	--	--	1	1
Total Credits				**15**	**0**	**9**	**20**

III Year – II SEMESTER

S. No	Course Code	Subjects	Category	L	T	P	Credits
1		Electric Drives	EE	3	--	--	3
2		Power System Analysis	EE	3	--	--	3
3		Data Structures	ES	3	--	--	3
4		Digital Control Systems	EE	3	--	--	3
5		**Elective - I**	EL	3	--	--	3
6		**Open Elective - I**	OE	3	--	--	3
7		Power Electronics Laboratory	EE	--	--	3	1.5
8		Microprocessors & Microcontrollers Laboratory	EE	--	--	3	1.5
9		Employability Skills	MC	3	--	--	0
Total Credits				**18**		**6**	**21**

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III Year – I SEMESTER		L	T	P	C
		3	0	0	3
	POWER SYSTEMS–II				

Preamble:
This course is an extension of power systems–I course. It deals with basic theory of transmission lines modeling and their performance analysis. Transient in power system, improvement of power factor and voltage control are discussed in detail. It is important for the student to understand the mechanical design aspects of transmission lines, cables, insulators. These aspects are also covered in detail in this course.

Learning Objectives:
- To compute inductance/capacitance of transmission lines and to understand the concepts of GMD/GMR.
- To study the short and medium length transmission lines, their models and performance.
- To study the performance and modeling of long transmission lines.
- To study the effect of travelling waves on transmission lines.
- To study the factors affecting the performance of transmission lines and power factor improvement methods.
- To discuss sag and tension computation of transmission lines as well as to study the performance of overhead insulators.

UNIT–I:
Transmission Line Parameters
Conductor materials - Types of conductors – Calculation of resistance for solid conductors – Calculation of inductance for single phase and three phase– Single and double circuit lines– Concept of GMR and GMD–Symmetrical and asymmetrical conductor configuration with and without transposition–Bundled conductors – Calculation of capacitance for 2 wire and 3 wire systems – Effect of ground on capacitance – Capacitance calculations for symmetrical and asymmetrical single and three phase–Single and double circuit lines- Bundled conductors.

UNIT–II:
Performance Analysis of Transmission Lines
Classification of Transmission Lines – Short, medium, long line and their model representations –Nominal-T–Nominal-Pie and A, B, C, D Constants for symmetrical and Asymmetrical Networks.

Rigorous Solution for long line equations – Surge Impedance and SIL of Long Lines – Representation of Long lines – Equivalent T and Equivalent Pie network models - Mathematical Solutions to estimate regulation and efficiency of all types of lines.

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UNIT – III:
Power System Transients
Types of System Transients – Travelling or Propagation of Surges – Attenuation–Distortion– Reflection and Refraction Coefficients – Termination of lines with different types of conditions – Open Circuited Line–Short Circuited Line – T-Junction– Lumped Reactive Junctions.

UNIT–IV:
Various Factors governing the Performance of Transmission line
Skin and Proximity effects – Description and effect on Resistance of Solid Conductors –Ferranti effect – Charging Current – Corona – Description of the phenomenon–Factors affecting corona– Critical voltages and power loss – Radio Interference.

UNIT–V:
Sag and Tension Calculations and Overhead Line Insulators
Sag and Tension calculations with equal and unequal heights of towers–Effect of Wind and Ice on weight of Conductor – Stringing chart and sag template and its applications–Types of Insulators – String efficiency and Methods for improvement - Voltage distribution–Calculation of string efficiency – Capacitance grading and Static Shielding.

Learning Outcomes:
After the completion of the course the student should be able to:
- understand parameters of various types of transmission lines during different operating conditions.
- understand the performance of short and medium transmission lines.
- understand travelling waves on transmission lines.
- understand various factors related to charged transmission lines.
- understand sag/tension of transmission lines and performance of line insulators.

Text Books:
1. Electrical power systems – by C.L.Wadhwa, New Age International (P) Limited, Publishers, 1998.
2. Modern Power System Analysis by I.J.Nagarath and D.P.Kothari, Tata McGraw Hill, 2nd Edition

Reference Books:
1. Power system Analysis–by John J Grainger William D Stevenson, TMC Companies, 4th edition
2. Power System Analysis and Design by B.R.Gupta, Wheeler Publishing.
3. A Text Book on Power System Engineering by M.L.Soni, P.V.Gupta, U.S.Bhatnagar A.Chakrabarthy, DhanpatRai& Co Pvt. Ltd.
4. Electrical Power Systems by P.S.R. Murthy, B.S.Publications.

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III Year – I SEMESTER		L	T	P	C
		3	0	0	3
	POWER ELECTRONICS				

Preamble:
The usage of power electronics in day to day life has increased in recent years. It is important for student to understand the fundamental principles behind all these converters. This course covers characteristics of semiconductor devices, ac/dc, dc/dc, ac/ac and dc/ac converters. The importance of using pulse width modulated techniques to obtain high quality power supply (dc/ac converter) is also discussed in detail in this course.

Learning Objectives:
- To study the characteristics of various power semiconductor devices and to design firing circuits for SCR.
- To understand the operation of single phase full–wave converters and analyze harmonics in the input current.
- To study the operation of three phase full–wave converters.
- To understand the operation of different types of DC-DC converters.
- To understand the operation of inverters and application of PWM techniques for voltage control and harmonic mitigation.
- To analyze the operation of AC-AC regulators.

UNIT–I:
Introduction
Basic Theory of Operation - Static Characteristics-Two Transistors analogy -Turn on and Turn off Methods - Methods of SCR Triggering - Dynamic & Gate Characteristics of SCR - Series and Parallel Operation - Snubber circuit - Characteristics of Power MOSFET and IGBT.

UNIT–II:
Single Phase AC-DC Converters
Single Phase half wave controlled rectifiers - R load and RL load with and without freewheeling diode - Single Phase fully controlled bridge converter with R load, RL load and RLE load - Continuous and Discontinuous conduction - Effect of source inductance in 1-phase fully controlled bridge rectifier with continuous conduction – Expression for output voltages – Single Phase semi Converter with R load, RL load and RLE load – Continuous and Discontinuous conduction - Harmonic Analysis - Single Phase Dual Converters - Numerical Problems

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UNIT–III:
Three Phase AC-DC Converters & AC – AC Converters
Three Phase half wave Rectifier with R and RL load -Three Phase fully controlled rectifier with R and RL load - Three Phase semi converter with R and RL load - Expression for Output Voltage - Harmonic Analysis - Three Phase Dual Converters - Numerical Problems.

AC-AC power control by phase control with R and RL loads - Three phase AC voltage regulator with R load – Single phase step down Cycloconverter - Numerical Problems.

UNIT–IV:
DC–DC Converters
Operation of Basic Chopper - Classification - Control Techniques - Analysis of Buck, Boost and Buck-Boost converters in Continuous Conduction Mode (CCM) and Discontinuous Conduction Modes (DCM) - Output voltage equations using volt-sec balance in CCM & DCM – Expressions for output voltage ripple and inductor current ripple- Numerical Problems.

UNIT – V:
DC–AC Converters
Introduction - Classification - Single Phase half bridge and full bridge inverters with R and RL loads - Unipolar & Bipolar Switching - Quasi-square wave pulse width modulation - Three Phase square wave inverters - 120^0 conduction and 180^0 conduction modes of operation - PWM inverters - Sinusoidal Pulse Width Modulation - Current Source Inverter (CSI) - Numerical Problems.

Learning Outcomes:
After the completion of the course the student should be able to:

- explain the characteristics of various power semiconductor devices and analyze the static and dynamic characteristics of SCR's.
- design firing circuits for SCR.
- explain the operation of single phase full–wave converters and analyze harmonics in the input current.
- explain the operation of three phase full–wave converters.
- analyze the operation of different types of DC-DC converters.
- explain the operation of inverters and application of PWM techniques for voltage control and harmonic mitigation.
- analyze the operation of AC-AC regulators.

Text Books:

1. Power Electronics: Converters, Applications and Design by Ned Mohan, Tore M Undeland, William P Robbins, John Wiley & Sons.

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2. Power Electronics: Circuits, Devices and Applications – by M. H. Rashid, Prentice Hall of India, 2nd edition, 1998
3. Power Electronics: Essentials & Applications by L.Umanand, Wiley, Pvt. Limited, India, 2009.

Reference Books:

1. Elements of Power Electronics–Philip T.Krein.oxford.
2. Power Electronics – by P.S.Bhimbra, Khanna Publishers.
3. Thyristorised Power Controllers – by G. K. Dubey, S. R. Doradla, A. Joshi and R. M. K.Sinha, New Age International (P) Limited Publishers, 1996.
4. Power Electronics: by Daniel W.Hart, Mc Graw Hill.

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III Year – I SEMESTER		L	T	P	C
		3	0	0	3
	LINEAR IC APPLICATIONS				

Preamble:

To understand the various possible applications of integrated circuits this course is proposed. To attend this course, it is assumed that all the students taking this course should have the basic electronic circuits' concepts. In the course content, basic characteristics required to use integrated circuits for various applications are included, followed by the linear and nonlinear applications of operational amplifiers. In addition, application of integrated circuits in filter design, modulators, analog multiplier, timer and phase locked loops applications. Application of integrated circuits for analog-to-digital and digital-to-analog conversion is also included.

Learning Objectives:

- To understand the basic operation &performance parameters of differential amplifiers.
- To understand & learn the measuring techniques of performance parameters of Op-Amp
- To learn the linear and non-linear applications of operational amplifiers.
- To understand the analysis & design of different types of active filters using Op-Amps
- To learn the internal structure, operation and applications of different analog ICs
- To Acquire skills required for designing and testing integrated circuits

UNIT I

Characteristics of OP-Amps:

Characteristics of OP-Amps, Integrated circuits-Types, Classification, Package Types and Temperature ranges, Power supplies, Op-Amp Block Diagram, ideal and practical Op-amp Specifications, DC and AC characteristics, 741 op-amp & its features, Op-Amp parameters & Measurement, Input & Out put Off set voltages & currents, slew rate, CMRR, PSRR, drift, Frequency Compensation techniques.

UNIT II

Linear And Non-Linear Applications Of Op-Amps:

Inverting and Non-inverting amplifier, Integrator and differentiator, Difference amplifier, Instrumentation amplifier, AC amplifier, V to I, I to V converters, Buffers. Non- Linear function generation, Comparators, Multivibrators, Triangular and Square wave generators, Log and Anti log Amplifiers, Precision rectifiers.

UNIT III

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Active Filters, Analog Multipliers And Modulators:
Design & Analysis of Butterworth active filters – 1st order, 2nd order LPF, HPF filters. Band pass, Band reject and all pass filters.
Four Quadrant Multiplier, IC 1496, Sample & Hold circuits.

UNIT IV
Timers & Phase Locked Loops:
Introduction to 555 timer, functional diagram, Monostable and Astable operations and applications, Schmitt Trigger; PLL - introduction, block schematic, principles and description of

individual blocks, 565 PLL, Applications of PLL – frequency multiplication, frequency translation, AM, FM & FSK demodulators. Applications of VCO (566).

UNIT V
Digital To Analog And Analog To Digital Converters:
Introduction, basic DAC techniques, weighted resistor DAC, R-2R ladder DAC, inverted R-2R DAC, and IC 1408 DAC, Different types of ADCs – parallel Comparator type ADC, counter type ADC, successive approximation ADC and dual slope ADC.DAC and ADC Specifications, Specifications AD 574 (12 bit ADC).

Learning Outcomes:
After the completion of the course the student should be able to:

- design circuits using operational amplifiers for various applications.
- analyze and design amplifiers and active filters using Op-amp.
- diagnose and trouble-shoot linear electronic circuits.
- understand the gain-bandwidth concept and frequency response of the amplifier configurations.
- understand thoroughly the operational amplifiers with linear integrated circuits.

Text Books:

1. Linear Integrated Circuits – D. Roy Choudhury, New Age International (p) Ltd, 2nd Edition,2003.
2. Op-Amps & Linear ICs - Ramakanth A. Gayakwad, PHI,1987.
3. Operational Amplifiers–C.G. Clayton, Butterworth & Company Publ. Ltd./Elsevier, 1971

References Books:

1. Operational Amplifiers & Linear Integrated Circuits –Sanjay Sharma ;SK Kataria &Sons;2nd Edition,2010
2. Design with Operational Amplifiers & Analog Integrated Circuits – Sergio Franco, McGraw Hill, 1988.

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3. OP AMPS and Linear Integrated Circuits concepts and Applications, James M Fiore, Cenage Learning India Ltd.
4. Operational Amplifiers & Linear Integrated Circuits–R.F.Coughlin & Fredrick Driscoll, PHI, 6th Edition.
5. Operational Amplifiers & Linear ICs – David A Bell, Oxford Uni. Press, 3rd Edition

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III Year – I SEMESTER		L	T	P	C
		3	0	0	3
	DIGITAL SIGNAL PROCESSING				

Preamble:
The course has been designed to cater to the needs of electronic industry transforms. This course covers basic concepts of signal processing, various transformation techniques. It provides students to relies about different filter structure and also coding of speech signals.

Learning Objectives:

- To explore the basic concepts of digital signal processing.
- To connect the time domain signal to frequency domain signals using fourier transform.
- To understand the basic structures of IRR systems.
- To understand and design FIR Digital filters.
- To explore the concepts of multiple sampling rates for DSP.

UNIT-I:
Introduction
Introduction to Digital Signal Processing: Discrete time signals & sequences, Classification of Discrete time systems, stability of LTI systems, Invertability, Response of LTI systems to arbitrary inputs. Solution of Linear constant coefficient difference equations. Frequency domain representation of discrete time signals and systems. Review of Z-transforms, solution of difference equations using Z-transforms, System function.

UNIT-II:
Discrete Fourier Series & Fourier Transforms
Properties of discrete Fourier series, DFS representation of periodic sequences, Discrete Fourier transforms: Properties of DFT, linear filtering methods based on DFT, Fast Fourier transforms (FFT) - Radix-2 decimation in time and decimation in frequency FFT Algorithms, Inverse FFT.

UNIT-III:
Design of IIR Digital Filters& Realizations
Analog filter approximations – Butter worth and Chebyshev, Design of IIR Digital filters from analog filters, Design Examples, Analog and Digital frequency transformations. Basic structures of IIR systems, Transposed forms.

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UNIT-IV:
Design of FIR Digital Filters & Realizations
Characteristics of FIR Digital Filters, frequency response. Design of FIR Digital Filters using Window Techniques and Frequency Sampling technique, Comparison of IIR & FIR filters.
Basic structures of FIR systems, Lattice structures, Lattice-ladder structures
UNIT-V:
Multirate Digital Signal Processing
Introduction, Decimation, Interpolation Sampling rate conversion, Implementation of sampling rate converters, Applications – Sub-band Coding of Speech Signals, Implementation of Digital Filter Banks, Trans-multiplexers.

Learning Outcomes:
After the completion of the course the student should be able to:

- understand the concepts of signal processing& transforms.
- appraise the Fat Fourier algorithm.
- design FIR and IIR filters.
- appreciate the concepts of multirate signal processing.

Text Books:

1. Digital Signal Processing, Principles, Algorithms, and Applications: John G. Proakis Dimitris G.Manolakis, Pearson Education / PHI, 2007.
2. Discrete Time Signal Processing – A.V.Oppenheim and R.W. Schaffer, PHI.
3. Digital Signal Processing – K Raja Rajeswari, I.K. International Publishing House.

Reference Books:

1. Digital Signal Processing: Andreas Antoniou, TATA McGraw Hill , 2006
2. Digital Signal Processing: MH Hayes, Schaum's Outlines, TATA Mc-Graw Hill, 2007.
3. DSP Primer - C. Britton Rorabaugh, Tata McGraw Hill, 2005.
4. Fundamentals of Digital Signal Processing using Matlab – Robert J. Schilling, Sandra L. Harris,Thomson, 2007.
5. Digital Signal Processing – Alan V. Oppenheim, Ronald W. Schafer, PHI Ed., 2006

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III Year – I SEMESTER		L	T	P	C
		3	0	0	3
MICROPROCESSORS AND MICROCONTROLLERS					

Preamble:
Microprocessor and Microcontroller have become important building blocks in digital electronics design. It is important for student to understand the architecture of a microprocessor and its interfacing with various modules. 8086 microprocessor architecture, programming, and interfacing is dealt in detail in this course. Interfacing, PIC, architecture, programming in C.

Learning objectives:
- To understand the organization and architecture of Microprocessor
- To understand addressing modes to access memory
- To understand 8051 micro controller architecture
- To understand the programming principles for 8086 and 8051
- To understand the interfacing of MP with IO as well as other devices
- To understand how to develop cyber physical systems

UNIT–I:
Introduction to Microprocessor Architecture
Introduction and evolution of Microprocessors – Architecture of 8086 – Memory Organization of 8086 – Register Organization of 8086 – Instruction sets of 8086 – Addressing modes – Assembler directives – Introduction to 80286, 80386, 80486 and Pentium (brief description about architectural advancements only).

UNIT–II:
Minimum and Maximum Mode Operations
General bus operation of 8086 – Minimum and Maximum mode operations of 8086 – 8086 Control signal interfacing – Read and write cycle timing diagrams.

Microprocessors I/O interfacing – I
8255 PPI– Architecture of 8255–Modes of operation– Interfacing I/O devices to 8086 using 8255–Interfacing A to D converters– Interfacing D to A converters– Stepper motor interfacing– Static memory interfacing with 8086.

UNIT–III:

Microprocessors I/O interfacing – II
Architecture and interfacing of 8251 USART – Architecture and interfacing of 8254 Timer/counter – Architecture and interfacing of DMA controller (8257) – Architecture 8259 Programmable Interrupt Controller (8259) – Command words and operating modes of 8259 –

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Interfacing of 8259 – Architecture of Keyboard/display controller (8279) – Modes of operation – Command words of 8279 – Interfacing of 8279.

UNIT–IV:
8051 Microcontroller:
Overview of 8051 Microcontroller – Architecture– Memory Organization – Register set – I/O ports and Interrupts – Timers and Counters – Serial Communication – Interfacing of peripherals-Instruction set.

UNIT– V:
PIC Architecture
Block diagram of basic PIC 18 micro controller – registers I/O ports – Programming in C for PIC: Data types, I/O programming, logical operations, data conversion.

Learning Outcomes:
After the completion of the course the student should be able to:

- understand the Microprocessor capability in general and explore the evaluation of microprocessors.
- understand the addressing modes of Microprocessors
- understand the Microcontroller capability
- program Microprocessors and Microcontrollers.
- interface Microprocessors and Microcontrollers with other electronic devices
- develop cyber physical systems

Text Books:

1. Ray and Burchandi, "Advanced Microprocessors and Interfacing", Tata McGraw–Hill.
2. Kenneth J Ayala, "The 8051 Microcontroller Architecture, Programming and Applications", Thomson Publishers, 2nd Edition.
3. PIC Microcontroller and Embedded Systems using Assembly and C for PIC 18, - Muhammad Ali Mazidi, RolindD.Mckinay , Danny causey -Pearson Publisher 21st Impression.

Reference Books:

1. Microprocessors and Interfacing, Douglas V Hall, Mc–Graw Hill, 2nd Edition.
2. R.S. Kaler, " A Text book of Microprocessors and Micro Controllers", I.K. International Publishing House Pvt. Ltd.
3. Ajay V. Deshmukh, "Microcontrollers – Theory and Applications", Tata McGraw–Hill Companies –2005.
4. Ajit Pal, "Microcontrollers – Principles and Applications", PHI Learning Pvt Ltd, 2011.

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III Year – I SEMESTER		L	T	P	C
		0	0	3	1.5
ELECTRICAL MACHINES – II LABORATORY					

Learning objectives:

- To control the speed of three phase induction motors.
- To determine /predetermine the performance three phase and single phase induction motors.
- To improve the power factor of single phase induction motor .
- To predetermine the regulation of three–phase alternator by various methods, find X_d/ X_q ratio of alternator and asses the performance of three–phase synchronous motor.

Any 10 of the following experiments are to be conducted:

1. Brake test on three phase Induction Motor
2. No–load & Blocked rotor tests on three phase Induction motor
3. Regulation of a three –phase alternator by synchronous impedance &m.m.f. Methods
4. Regulation of three–phase alternator by Potier triangle method
5. V and Inverted V curves of a three—phase synchronous motor.
6. Determination of X_d and X_q of a salient pole synchronous machine
7. Equivalent circuit of single phase induction motor
8. Speed control of induction motor by V/f method.
9. Determination of efficiency of three-phase alternator by loading with three phase induction motor.
10. Power factor improvement of single-phase induction motor by using capacitors and load test on single-phase induction motor.
11. Parallel operation of three-phase alternator.
12. Brake test on single-phase AC series Motor.
13. Starting methods of a capacitor start and capacitor start run single-phase Induction motor.
14. Brake test on single-phase Induction Motor.

Learning outcomes:

After the completion of the course the student should be able to:

- assess the performance of single phase and three phase induction motors.
- control the speed of three phase induction motor.
- predetermine the regulation of three–phase alternator by various methods.
- find the X_d/ X_q ratio of alternator and asses the performance of three–phase synchronous motor.
- determine the performance single phase AC series motor.

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III Year – I SEMESTER		L	T	P	C
		0	0	2	1
CONTROL SYSTEMS LABORATORY					

Learning Objectives:

- To impart hands on experience to understand the performance of basic control system components such as magnetic amplifiers, D.C. servo motors, A.C. Servo motors and Synchros.
- To understand time and frequency responses of control system with and without controllers and compensators.

Any 10 of the following experiments are to be conducted:

1. Time response of Second order system
2. Characteristics of Synchros
3. Effect of P, PD, PI, PID Controller on a second order systems
4. Design of Lag and lead compensation – Magnitude and phase plot
5. Transfer function of DC motor
6. Bode Plot, Root locus, Nyquist Plots for the transfer functions of systems up to 5^{th} order using MATLAB.
7. Controllability and Observability Test using MAT LAB.
8. Temperature controller using PID
9. Characteristics of magnetic amplifiers
10. Characteristics of AC servo motor
11. Characteristics of DC servo motor
12. Block Diagram Representation of Field Controlled DC servo Motor Using Simulink.

Learning Outcomes:

After the completion of the course the student should be able to:

- analyze the performance and working Magnetic amplifier, D.C and A.C. servo motors and synchros.
- design P,PI,PD and PID controllers
- design lag, lead and lag–lead compensators
- control the temperature using PID controller
- determine the transfer function of D.C Motor
- control the performance of D.C and A.C Servo Motor.
- test the controllability and observability.
- judge the stability in time and frequency domain.

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III Year – I SEMESTER		L	T	P	C
		0	0	3	1.5

ELECTRICAL MEASUREMENTS & INSRUMENTATION LABORATORY

Learning Objectives:

- To understand the correct function of electrical parameters and calibration of voltage, current, single phase and three phase power and energy, and measurement of electrical characteristics of resistance, inductance and capacitance of a circuits through appropriate methods.
- To understand the calibration of DC and AC Potentiometers.
- To understand the testing of CT and PT.
- To Understand and the characteristics of Thermo couples, LVDT, Capacitive transducer, piezoelectric transducer.
- To understand the measurement of strain, Phase difference and frequency.

Any 10 of the following experiments are to be conducted

1. Calibration of dynamometer wattmeter using phantom loading
2. Crompton D.C. Potentiometer - Calibration of PMMC ammeter and PMMC voltmeter
3. Kelvin's double Bridge - Measurement of resistance - Determination of tolerance.
4. Capacitance Measurement using Schering Bridge.
5. Inductance Measurement using Anderson Bridge.
6. Calibration of LPF Wattmeter – by direct loading.
7. Measurement of 3 phase power with single watt meter and 2 No's of C.T.
8. Testing of C.T. using mutual inductor – Measurement of % ratio error and phase angle of given C.T. by Null method.
9. P.T. testing by comparison – V.G as Null detector – Measurement of % ratio error and phase angle of the given P.T.
10. AC Potentiometer – Polar form/Cartesian form – Calibration of AC Voltmeter, Parameters of Choke
11. Thermocouple – characteristics
12. LVDT – characteristics.
13. Capacitive transducers characteristics.
14. Piezoelectric transducer characteristics.
15. Measurement of strain using strain gauge
16. Measurement of phase difference, frequency using Lissajous patterns in CRO.

Learning Outcomes:

After the completion of the course the student should be able to:

- measure the electrical parameters voltage, current, power, energy and electrical characteristics of resistance, inductance and capacitance.
- known the characteristics of transducers.
- measure the strains, frequency and phase difference.

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III Year – I SEMESTER		L	T	P	C
		0	0	1	1
SOCIALLY RELAVENT PROJECTS					

Preamble:
There is lot of scientific and technological changes in the nation during last few decades in almost all the sectors. The state and central governments are introducing many schemes to all classes of people of the nation to increase the productivity in various sectors. India is a rural centric nation and the fruits of the scientific inventions and new technology shall be shared among all remote corners of the nation. With this aim, a socially relevant project is newly introduced in the curriculum with an objective of taking up the projects relevant to the societal needs.

Objectives:
(1) The student(s) shall explore the technological needs of society
(2) The student(s) shall understand the technological problems of society

General guidelines:

- A socially relevant project shall be a community service based project and it shall be innovative.
- A student has to pursue the socially relevant project to solve real life and pressing problems of society.
- The pursued socially relevant projects shall contribute to national development goals and priorities.
- Socially relevant project can be carried out by an individual student or by a team of maximum 5 of concerned department.
- The student(s) shall visit the society (Villages/Hospitals/Social Service Organizations etc) to identify the problem and conduct literature survey and provide a feasible solution.
- The socially relevant project selected shall be in the broad area of concerned discipline of course. Preference shall be given to rural societal problems.
- Each team shall work under the supervision of a faculty member of the concerned department.
- If the course is offered in II Year I Semester, the student or team of students shall complete this project during the vacation after I Year and so on.
- The duration of the project is about 15 to 20 hrs in total and students may split total duration into 2 to 3 hrs per day based convenience. The attendance shall be maintained by the supervisor.

Sample Projects (but not limited to):
(i) Energy Auditing in a rural village (ii) Smart starting and control of motors in agriculture and aqua fields (iii) TV Remote Operated Domestic Appliances Control (iv) Solar Powered Auto Irrigation System (v) Auto Intensity Control of Street Lights (vi) Hidden Active Cell Phone Detector (vii) Railway Track Security System (viii) Solar

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Power Charge Controller (ix) Home Automation System Using Digital Control (x) Intelligent Overhead Tank Water Level Indicator (xi) Pre Stampede Monitoring and Alarm System (xii) Detect Rash Driving Speed Checker System on Highways

Outcomes

(1) The student(s) are be able to provide a solutions the technological problems of society
(1) The student(s) is able suggest technological changes which suits current needs of society
(2) The student(s) are able to explain new technologies available for problems of the society.

Reference:

(1) Web Link: http://iitk.ac.in/new/socially-relevant-research
(2) https://csie.iitm.ac.in/SocialProjectsIITM.html
(3) http://www.iitkgp.ac.in/files/csr/csr_education.pdf